LINE SEIKI

INSTRUCTION MANUAL

G 2 O SERIES PRESET COUNTER

G 2 0 -0 🗆 🗆 🗆 4000 5 🗆 🗆 🗆 $2 \square \square \square$ 3 🗆 🗆 🗆

- * Before you use G20 series, please read this manual to use this counter correctly.
- * Keep this manual carefully.
- * Contents of this manual are subject to change without notice.

With reading this instruction manual, use correctly before fixing, operating, maintaining and examining.

NOTICE

O N

Keep the following notices not to cause electric shock, injury and damage of device.



To prevent from the dangerous condition of user's death or heavy injury, look through the following warning.



♦ Supply the voltage between the terminal No. 29 & No. 30 of unit in the range of 85-264VAC. Be sure to confirm the voltage not to cause destruction of the unit by supplying the voltage out of applicable range.



◇Be sure to confirm if there is problem such like looseness of screw, wrong wiring..etc., after wiring.



♦Do not take the unit apart or modify.

<REQUESTS>

SAFETY

♦Do not use the unit under the following evnironment.

· Explosive gas, Inflammable gas, Corrosive gas.

· High humidity, Dewdrop.

· Intensive temperature difference

· Intensive vibration.

◇Do not drop or give the high shock to the counter.

♦Be sure to use load current within nominal.

Keep away the wiring from the high voltage or current lines.

◇Do not use the blank terminals as relay terminal.

♦ Keep the input signal source, counter itself or it's wiring away from the noise source when the counter is used in the noise. It is effective to make the wireleads for input to be shielded.

♦In case there are surge and noise on power supply, connect the line noise filter with counter.

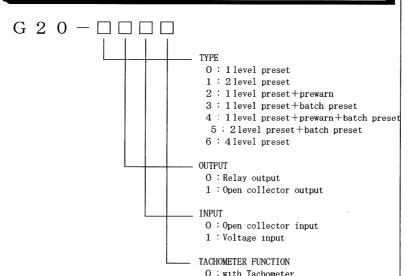
 \diamondsuit In case of wiring for the communication cable outside, equip the baristor to prevent the counter from the lightning shock.

OPay attention to the excessive fastening for the screw of terminal and panel clamper.

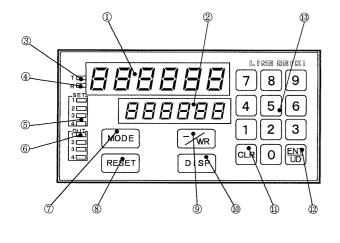
FEATURES

- · Easy operation by 10 keys
- \cdot Power supply, 100-240VAC
- · Prescale function
- · Tachometer function
- Communication function (RS-485)
- · Programmable count start value
- \cdot D I N 7 2 × 1 4 4 mm
- · Depth, 66 mm. Compact size
- · Dust & Splash proof

MODEL



FRONT PANEL FEATURES



- Display for count value, tachometer value, and programming items
- Display for preset value and programmed data Indicator for total counter
- 4 Indicator for tachometer
- Indicator for SET 1 1 level preset - 2 level preset preset value:

- 3 level preset - 4 level preset Prewarn

Batch preset 6 Indicator for OUT 1 level preset output - 2 level preset output

1 2) SIZE

13) WEIGHT

- 3 level preset output 3 - 4 level preset output - Prewarn output Ρ

DIN72×144mm

approx. 360 g

Batch output Mode key

- Reset Key
- -/WR key (10) DISP key
- (11) CLR key
- ENT/UD key
- (3) 10 keys (0 9)

ELECTRIC SPECIFICATIONS

- 1) POWER SUPPLY
- $100 \sim 240 \text{ VAC} 15\%, +10\%$ 2) POWER CONSUMPTION

※The design of front membrane is different

according to each models.

- approx. 7 V A
- 3) SENSOR POWER SOURCE
- $12VDC \pm 10\% 100mA$ max. 4) MEMORY
- EEPROM (10 years: can be used 100,000 times) 5) OPERATING TEMPERATURE
- $-10\sim50$ °C (NON FREEZING)
- 6) OPERATING HUMIDITY
 - 45~85%RH (NON CONDENSING)
- 7) INSULATION RESISTANCE
- $100M\Omega$ (at 500VDC) minimum
- 8) TEST VOLTAGE 1500VAC for one (1) minute
- 9) TEST NOISE
- Between the terminal on power supply : $\pm 2000 \text{ V}$ Between the terminal on signal input : ± 500 V
- 1 O) TEST OSCILLATION
- - Endurance: 10 \sim 55 Hz, amplitude 1.5 mm, 3 hours(1 cycle 3 minutes) to X,Y,Z 3 directions Operation: 1 0 \sim 5 5 H z, amplitude 1. 5 mm, 3 hours(1 cycle 3 minutes) to X,Y,Z 3 directions
- 1 1) TEST SHOCK
- - Endurance: $3~0~0~m/s^2$ (approx 3~0~G) 10 times to X, Y, Z 3 directions Operation: $1~0~0~m/s^2$ (approx 1~0~G) 10 times to X, Y, Z 3 directions

SPECIFICATIONS

1) DISPLAY

Upper display: Red LED 14.22(H) x 7.8(W) Lower display: Green LED 10.00(H) x 5.5(W)

2) NUMBER OF DIGITS

Upper display: Preset counter 6 digits Totalizer 6 digits Tachometer 6 digits

Batch counter 6 digits Lower display: Preset value 6 digits

3) INDICATOR

Yellow LED: It turns on when the display is totalizer & tachometer. Green $\ensuremath{\mathsf{LED}}$: It turns on when the display shows preset value.

LED: It turns on when the unit let out the output signal.

4) SETTING WAY

10 keys (numerical keys) operation

5) SETTING RANGE

Preset value (P 1 \sim P 4) : -99999 \sim 999999 Prewarn value (PW) $0 \sim 9999999$ Batch preset value (PB) : 0~999999 6) PRESCALE

Multiplying : 0. 00001 \sim 999. 999 Dividing : 1 \sim 9997 DECIMAL POINT POSITION

 $0.0 \sim 0.0000$ 8) COUNT START VALUE

 $-99999 \sim 999999$ 9) INPUT

· Open collector input

Sink current: 10mA L:0~6V

· Voltage input

 $H:6\sim3~0~V~$ (Input impedance $7~k~\Omega$) $L\,:\,0\,{\sim}\,4\,V$ 1 O) COUNT SPEED

30Hz (Pulse width 16ms Duty 1:1) 1 k H z (Pulse width $500 \mu \text{ s}$ Duty 1:1) 5 k H z (Pulse width $100 \mu \text{ s} \text{ Duty } 1:1)$

8 kHz (Pulse width $62.5 \mu \text{ s}$ Duty 1:1) 1 1) TYPE OF INPUT SIGNAL

Add/Subtract/Individual add, subtract/Quadrature

12) OPERATION

Overrun/Auto-reset/Equal/Upper-lower limit

Model with prewarn function, not include Upper-lower limit Model with batch function, not include Upper-lower limit/Equal

One shot pulse/Latch

14) OUTPUT TIME

 $10\,\mathrm{m}\,\mathrm{s} \sim 9\,9\,9\,0\,\mathrm{ms}$ (Available to set with $10\,\mathrm{m}\,\mathrm{s}$ in one unit) 15) TYPE OF OUTPUT

· Relay output

1 c (250VAC 3A/30VDC 3A resistance load) • Open collector output

(30 VDC 100 mA max.) 16) OUTPUT DELAY TIME

6 ms max. 17) RESET

Front reset

Remote reset

Prohibition for front key reset, preset value editing, count start

value editing or editing data in program mode. 19) TACHOMETER

> 1/TAU, Star ndard sampling (Measuring accuracy: ±0 1%) What is 1/TAU?

The 1/TAU method of rate calculation is based on accurately measuring the time period between consecutive input pulses. This time period is called "TAU".

20) COMMUNICATION

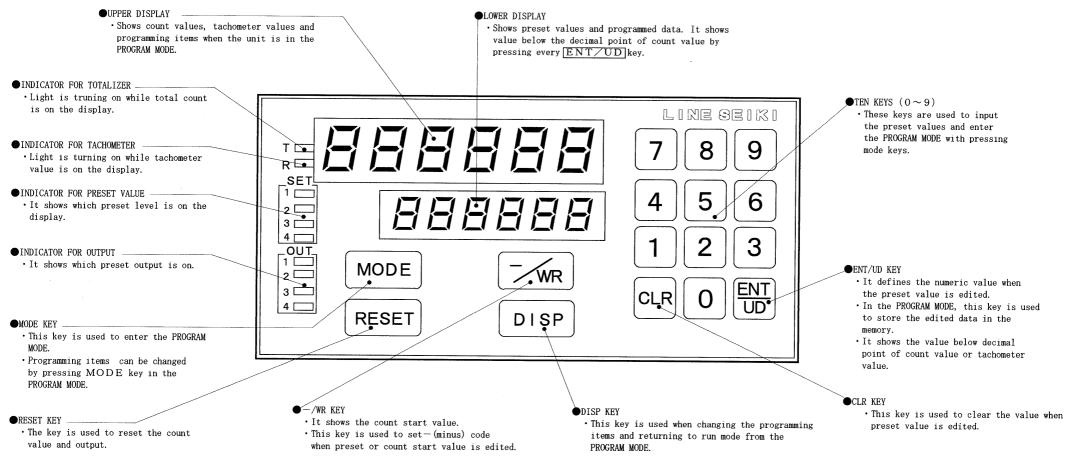
RS-485 Serial interface

Read count value, preset value or count start value.

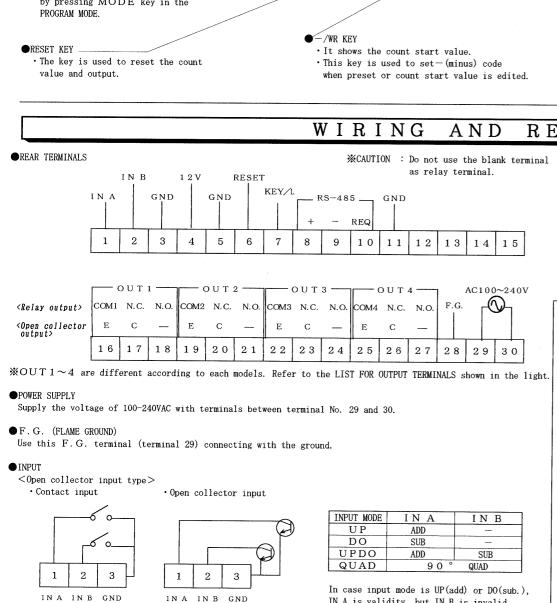
Send preset value or count start value.

Read the condition of reset and preset output condition.

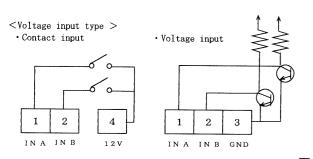
FEATURES FRONT PANEL



A N D REAR TERMINALS



IN A is validity, but IN B is invalid.



● OUTPUT Refer to the REAR TERMINALS and the LIST FOR OUTPUT TERMINALS.

●REMOTE RESET By shorting the terminals between "No. 6" and "GND", count value and output will be reset. (Under shorting, counter does not accept for any input pulse) KEY LOCK

By shorting the terminals between "No. 7" and "GND", programming or editing selected in KEY LOCK MODE is invalid. 5

KEY/I

((NOTE))

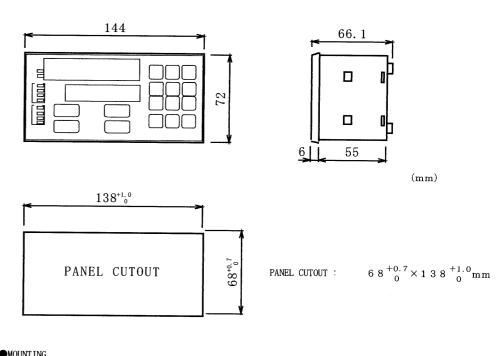
- · Be sure to turn the power supply off in case of doing the wiring.
- · Supply the voltage at the range of 85-264VAC between the terminal
- · Confirm the looseness of screw, wrong wiring..etc., after wiring.
- · Avoid the excessive fastening for
- terminal of the unit.

●LIST FOR OUTPUT TERMINALS

型式	OUT1	OUT 2	OUT3	OUT4
G20 - 0 -	OUT	_	-	
1 🗆 🗆	OUT1	OUT 2	-	TOWNS.
2 🗆 🗆	PREWARN	OUT	_	****
3 □ □ □	OUT	BATCH	_	_
4 🗆 🗆	PREWARN	OUT	BATCH	_
5 🗆 🗆	OUT1	OUT 2	BATCH	_
6 🗆 🗆	OUT1	OUT 2	OUT 3	OUT 4
				(-: NOT AVAILABLE)

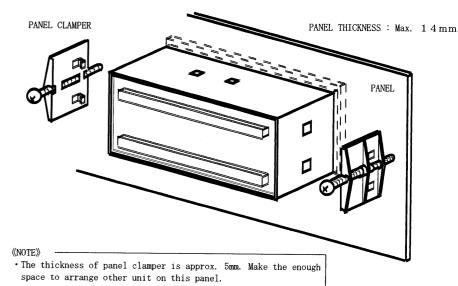
DIMENSIONS AND MOUNT

●EXTERNAL DIMENSIONS



MOUNTING

Insert the unit from front side of panel, and hang the nails of panel clamper on both side or upper-lower side of the unit, and fix the unit by fastening the screw.



- - · Avoid the excessive fastening for the screw of panel clamper.

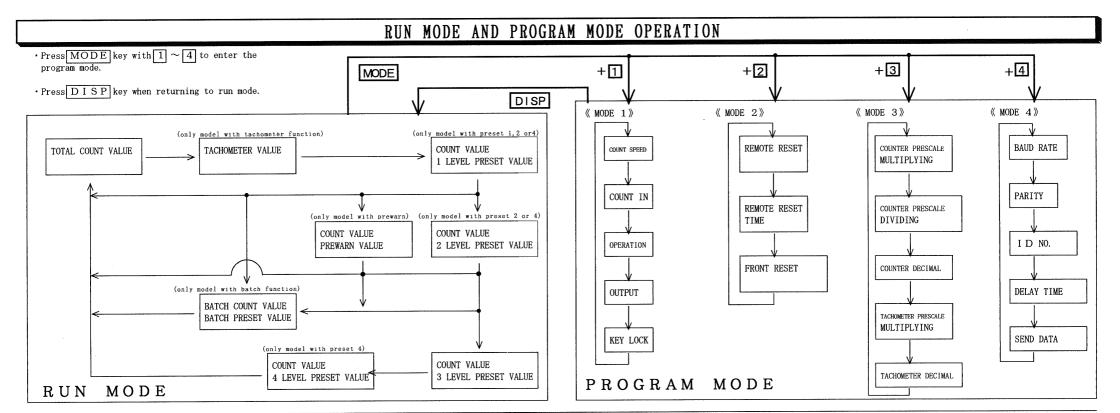
ullet SERIAL COMMUNICATION (RS-485) Use the terminal No. 8 and 9 in case communication is required.

● COMMUNICATION REQUEST

By shorting the terminals between "No. 10" and "GND", it will be available to read the data easily.

SENSOR POWER SOURCE

Terminal No. 4 is used as the sensor power source. (12VDC \pm 10% 100mA max.)



DETAILS OF PROGRAM MODE

NOTE: Depending on the models, programming items marked "%" do not apply to all models. % MODE 1%

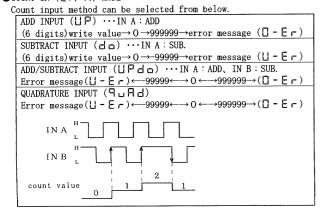
Η,.

Н, .

●COUNT IN ([., ¬) MODE

5 k H z

8 k H z



●OPERATION ([.月亡上) MODE ※
Operation method can be selected from below

Ų	peration metr	100	can be selec
	OVER RUN		0 4
	AUTO-RESET		A.res
	EQUAL	*	E 9 u .
į	TIDDED /T OWED	X 4	1111 1 1

UPPER/LOWER ※ | LL.LL |
UPPER/LOWER limit is not equipped for the model with prewarn.
EQUAL and UPPER/LOWER limit are not equipped for the model
with batch

●OUTPUT (□⊔E 1~□⊔EЧ) MODE ※

When OPERATION MODE is set to OVERRUN or AUTO-RESET, HOLD or ONE SHOT can be selected in OUTPUT MODE. When OPERATION MODE is EQUAL or UPPER/LOWER, HOLD is automatically set. Programming of OUTPUT MODE on each preset level is available.

HOLD Hold at the preset value Overrun Auto-reset

ONE SHOT On E. 5 Programming is available at Overrun 10ms each in 10~9990ms Auto-reset

· Refer to the following list of output corresponding to each model

1	for the setting.					
	MODEL	OUT1	OUT 2	OUT3	OUT4	
	G20−0 □□□	OUT	_	_		
	1000	OUT 1	OUT 2	_		
	2 🗆 🗆 🗆	PREWARN	OUT	-	_	
	3 🗆 🗆 🗆	OUT	BATCH	_		
	4 🗆 🗆 🗆	PREWARN	OUT	BATCH		
	5 🗆 🗆 🗆	OUT1	OUT 2	BATCH	_	
	6 🗆 🗆 🗆	OUT1	OUT 2	OUT3	OUT4	

●KEY LOCK (□ P E r : KEY OPERATION LOCK) MODE

Key operation to be abled or disabled can be selected.

	OPERATION, YES	OPERATION, NO
FRONT RESET	r 85. Y	r 25. n
CHANGE ON PRESET VALUE	Pr2.Y	Pre.n
CHANGE ON CNT. ST. VAL. *	C.50.4	C.58.n
CHANGE ON MODE 1	PG 1. Y	PG 1.n
CHANGE ON MODE 2	PG2.Y	PG2.n
CHANGE ON MODE 3	PG3.4	PG3.n
CHANGE ON MODE 4	P G 4. Y	P G 4. n

* CNT. ST. VAL. = COUNT START VALUE

$\langle\!\langle$ MODE 2 $\rangle\!\rangle$

●REMOTE RESET (E. - 25) MODE ※
Remote reset to be abled or disabled can be selected.

		RESET,	YES	RESET,	NO	
PRESET COUNTER		PC	Ч	PE	П	
BATCH COUNTER	*	ЬС	4	ьE	п	
TOTAL COUNTER		FΓ	Ч	⊢ □	п	

●REMOTE RESET TIME (「₽5. と) MODE

Either can be selected.

1 m s
2 0 m s
2 0

This time means minimum pulse time required for remote reset pulse.

●FRONT RESET (F. - ₽5) MODE ※

Front reset to be abled or disabled can be selected.

	RESET, YES	RESET, NO
PRESET COUNTER	PC Y	PC n
BATCH COUNTER 💥	PC A	b[n
TOTAL COUNTER	 - - -	l FF o

《 MODE 3》

●COUNTER PRESCALE(dividing) ([.d. u) MODE Counter prescale can be set in following range. 1 ~ 9999

0.00000	0.00000
0. 0000	0.0000
0.000	0.000
0.00	0.00
0. 0	0.0
None	

— 《NOTE》 − •If decimal

• If decimal point position is changed, the present preset value, count value, etc. are cleared.

- ●TACHOMETER PRESCALE(only multiplying) (Ł. P 5) MODE ※ Only the model with tachometer is available to be set tachometer prescale as same as counter prescale.
- ●TACHOMETER DECIMAL POINT POSITIONING (上. 日 P) MODE ※
 Decimal point position for tachometer value can be set as same as counter decimal point position.

《 MODE 4》

●BAUD RATE (ЬР5) MODE

AUD RAIE (BF 3) MODE					
ransmit speed	can be selected	from	the	below.	
9600bps	9600				
4800bps	4800				
2400bps	2400				
1 2 0 0 bps	1200				
6 0 0 bps	600				
3 0 0 bps	300				

● PARITY BIT (P. b. E) MODE

Parity bit can be s	elected from the be
non parity	None
even no. parity	Euen
odd no. parity	044

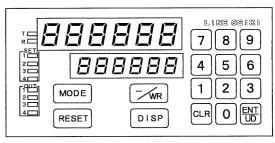
● I D NUMBER (1 d) MODE

ID number can be selected in the range of $\Box\Box\sim 99$.

● SEND DATA (5日nd) MODE ※

Transmit data can be programmed on the following items.

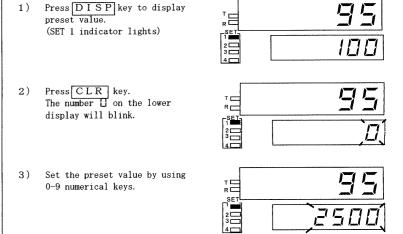
	SEND	NOT SEND
PRESET COUNT VALUE	PC Y	PEn
BATCH COUNT VALUE 💥	PC A	b[n
TOTAL COUNT VALUE	FC A	LC n
1 LEVEL PRESET VALUE	P 1 Y	Pla
2 LEVEL PRESET VALUE 💥	PS 4	P2 n
3 LEVEL PRESET VALUE 💥	P3 Y	P3 n
4 LEVEL PRESET VALUE 💥	PY Y	P4 n
PREWARN VALUE **	Pn y	Paa
BATCH PRESET VALUE 💥	Pb A	ЬР л



HOW TO PROGRAM PRESET VALUE

The preset value can be programmed in the RUN MODE.

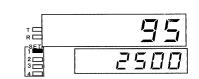
EXAMPLE: Change of the preset value from 100 to 2500.



• For minus value input, press -/WR key first.

 Press CLR key to cancel the set value. In this case, the lower display shows previous preset value.

4) Press ENT/UD key to determine the preset value. (Blinking stops and the setting is completed)

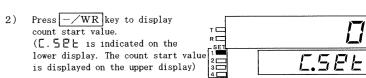


**How to set or change the preset value is all the same in any models.

HOW TO PROGRAM COUNT START VALUE

The count start value can be programmed in the RUN ${\tt MODE}$

1) Make preset count value show.



3) Press CLR key. [] will be blink.

4) Set the count start value by using numerical keys.

• Press —/WR key first when the setting value is minus.
• Press CLR key to clear the set value.

In this case, the lower display shows the previous value.

5) Press $\boxed{\text{ENT/UD}}$ key to determine the count start value. (Blinking stop, and setting is completed)

6) Press -/WR key to make the display shows the preset count value.

 By front key reset or remote reset on, the count start value can be shown on the upper display.

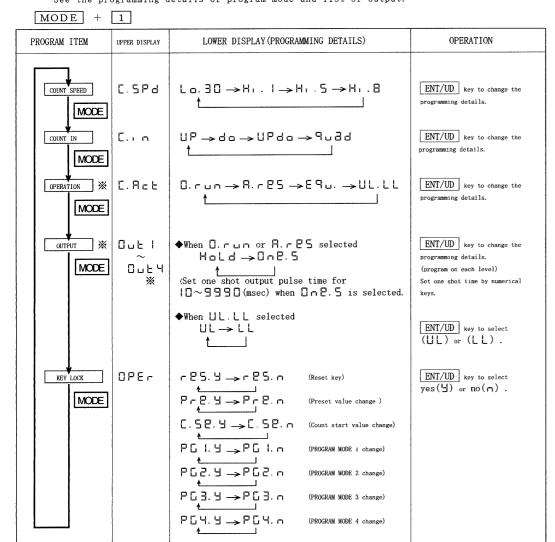
BATCH FUNCTION

MODEL G 2 0 - 3 \square \square , 4 \square \square , 5 \square \square have batch function. G 2 0 - 3 \square \square , 4 \square \square \square : One count is added when the counts reached

to the 1 level preset value. G 20-5 \square \square : One count is added when the counts reached to the 2 level preset value.

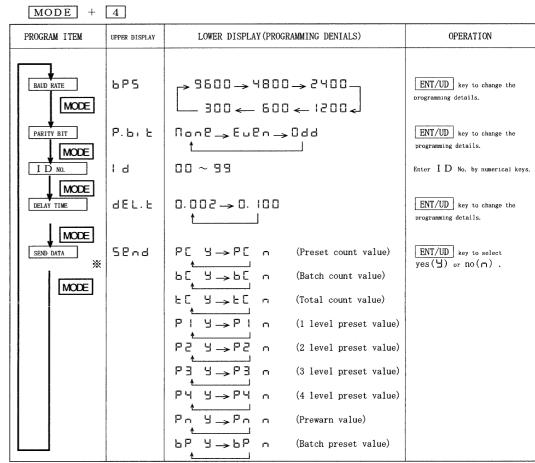
OPERATION OF PROGRAM MODE

NOTE:Depending on the models, program items marked % do not apply to all models. See the programming details of program mode and list of output.



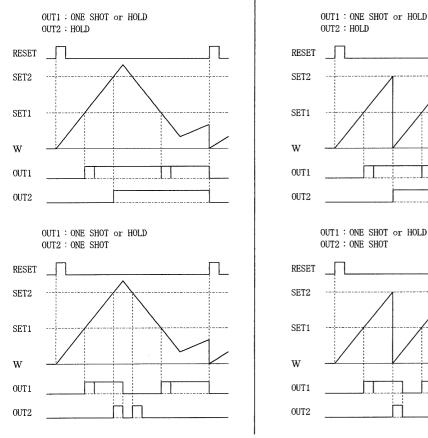
MODE +	2		
PROGRAM ITEM	UPPER DISPLAY	LOWER DISPLAY (PROGRAMMING DETAILS)	OPERATION
REMOTE RESET **	E.r.85	P[Y→P[n (Preset counter) b[Y→b[n (Batch counter) b[Y→b[n (Total counter)	ENT/UD] key to select yes(님) or no(n).
REMOTE RESET TIME	r 85. E	! →20 1	ENT/UD key to change the programming details.
FRONT ** RESET ** MODE	F.r05	P[Y→P[n (Preset counter) b[Y→b[n (Batch counter) t[Y→b[n (Total counter)	ENT/UD key to select yes(当) or no(n).

MODE + 3PROGRAM ITEM HPPER DISPLAY LOWER DISPLAY (PROGRAMMING DETAILS) OPERATION <mark>→</mark>0.001~999.999 C.P5 ENT/UD key to change decimal COUNTER PRESCALE (MULTIPLYING) point position 0.0001~99.9999 Enter prescale value by numerical MODE keys. L o. 0000 1 ~ 9. 99999 [. d. u 1~9999 COUNTER PRESCALE Enter prescale value by numerical (DIVIDING) MODE C. dP →0.0 →0.00 →0.000 -ENT/UD key to change COUNTER DECIMAL POINT programing details. └0.00000 ← 0.0000 ← MODE **→** 0.00 l ~ 999.999 E.PS ENT/UD key to change TACHO, PRESCALE (MULTIPLYING) decimal point position. 0.0001~99.9999 Enter prescale value by numerical MODE L a. a°aaa 1 ~ 9. 99999 →0.0 →0.0 →0.00 -E. dP ENT/UD key to change TACHOMETER DECIMAL POINT programming details. └ 0.00000 ← - 0.0000 ← MODE

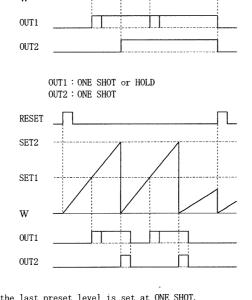


COUNT AND OUTPUT (1)

●G 2 O - O □ □ □ 、1 □ □ 、3 □ □ 、5 □ □ 、6 □ □ □ (MODEL FOR 1 LEVEL, 2 LEVEL, 4 LEVEL or WITHOUT PREWARN)

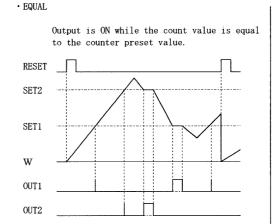


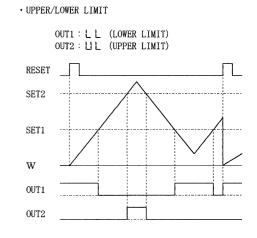
· OVER RUN



• For 2 level or 4 level preset type, when output of the last preset level is set at ONE SHOT,

all outputs are turned to OFF by the falling edge of ONE SHOT pulse.



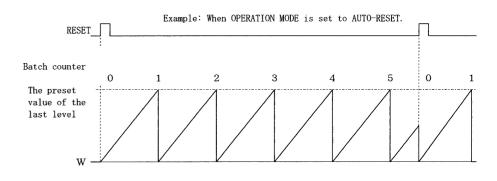


Output of each preset levels is individual each other. Refer the above drawings. ${\tt EQUAL}$ and ${\tt UPPER/LOWER}$ limit are not selectable on the model with Batch function.

●BATCH FUNCTION

G 2 0 - 3 $\square\square\square$, 5 $\square\square\square$ have Batch function.

Batch counter counts 1 when the count value reaches to the preset value of the last level.



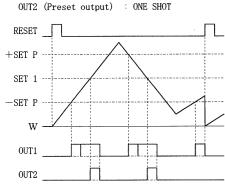
COUNT AND OUTPUT

lacktriangle G 2 0 - 2 $\Box\Box\Box$, 4 $\Box\Box\Box$ (1 level with prewarn)

Model with prewarn has no UPPER/LOWER output in the OPERATION MODE. For G 2 O - 4 \square \square , the model with batch function, EQUAL output is not available and only OVERRUN or AUTO-RESET is available in OPERATION MODE. OUT 1 is prewarn output, OUT 2 is preset output. On the model with batch function, OUT 3 is batch output.

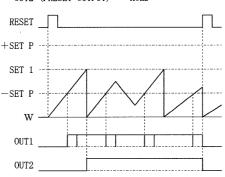
· OVER RUN OUT1 (Prewarn output) : ONE SHOT or HOLD OUT2 (Preset output) : HOLD RESET +SET P SET 1 -SET P OUT1

OUT1 (Prewarn output) : ONE SHOT or HOLD

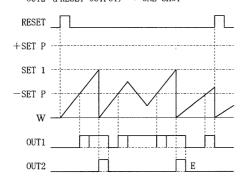


· AUTO RESET

OUT1 (PREWARN OUTPUT) : ONE SHOT or HOLD OUT2 (PRESET OUTPUT) : HOLD

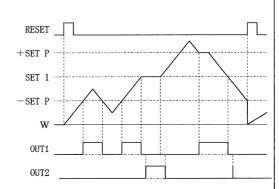


OUT1 (PREWARN OUTPUT) : ONE SHOT or HOLD OUT2 (PRESET OUTPUT) : ONE SHOT



- · When OUT 2 (Preset output) is set to ONE SHOT, OUT 1 (Prewarn Output) turns to be OFF by the falling edge of that ONE SHOT pulse.
- · Prewarn output is ON only when the count value is near to SET1 (1 level preset value).

• EQUAL(Only for the model without batch function) OUT 1 (Prewarn output) is ON only when the count value is near to SET1 (1 level preset value). $O\,U\,T\,2\,\mbox{(Preset output)}$ is ON only when the count value is equal to SET1.



RESET

●Type of reset

- · Front reset
- Remote reset *
- · Reset by serial communication command
- * Does not count during shorting
- •Subject to be reset:
- Count value (Preset count value) and output
- · Total count value · Batch count value
- Error (Overflow , Underflow)

Reset able or disable are can be selected in the PROGRAM MODE.

Reset of count value (Preset count value) enables all preset outputs to be OFF.

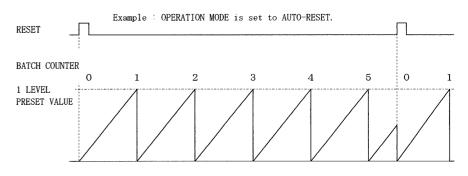
The determined count start value can be shown on the upper display by reset ON.

The count start value at ex-fact is set to 0.

●BATCH OUTPUT

G 2 0 - 4 \square \square has Batch function.

Batch counter counts 1 when the preset counter reaches 1 level preset value. The batch output turns ON when the batch count reaches the batch preset value. For the batch output, ONE SHOT or HOLD can be selected.



SERIAL COMMUNICATION (1)

- ●The control uses ASCII code with the RS-485 serial specification.
- ●This allows bi-directional communications and addressing of multiple controls on a single two-wire communication bus.
- ●Each unit is individually addressed via a user programmable ID number. Up to 32 G20 counters can be connected directly to the bus.

፠SERIAL COMMAND SUMMARY

RDD Read count value/preset value. (display only)

(value of integral number) RDI11 RDU (value of under decimal point)

WRD Write preset value.

RES Reset for count value and condition of over/under flow error.

RDO Read output condition.

STP Count prohibition. RSM Cancellation for count prohibition.

LTD Store count value/preset value in memory of counter.

Read stored data by LTD command. RLD

((NOTE))

- · It can not be to communicate if the count input pulse speed goes over the max. count speed.
- · Use only the character of capital letter in communication.

◆ TRANSMISSION FORMAT

The general command is shown below. Spaces are used for clarify only and must not be transmitted.

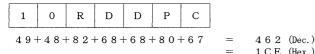
> I D # COMMAND (numerical data) CHECKSUM (cr)

Example: To cause the unit #10 to transmit the value of main counter, send the RDD command as follows.



- ① Message start character (ASCII 62). Required for all transmission to the control.
- Two digits serial port ID# in decimal. Required for all transmission to the control. Unit ID#10 (decimal) is unit ID#0A (hexadecimal), capital letters must be used.
- ③ RDD command. All serial commands consist of three characters.
- Sub command decides the details for serial command. This command means the read of preset count value by PC.
- ⑤ Checksum

CHECK SUM CALCULATION



Check sum is the last two hexadecimal charring.

The > start character and carriage return (c r) are not used in calculation.

⑥ ASCII carriage return (13 decimal). Required at the end of all commands.

◆ RESPONSE FORMAT

RESPONSE RECOGNITION FORMAT

The counter does not respond to a command unless the transmitted ID number matches its programmed ID number.

If the ID numbers match and the command and checksum are valid, the control executes the command and transmits a response as shown below.

[A] [DATA] [CHECK SUM] (cr)

[A] is the acknowledge character sent when any valid command is received and executed.

[DATA] is sent in response to request data.

[CHECK SUM] is sent only when data is requested (RDD, RDI or RDU commands).

The checksum is calculated by adding the ASCII values of all preceding characters (including the "A" and spaces). The checksum is the two least significant digits of. this sum in hexadecimal.

(cr) is the ASCII carriage return (13 decimal). Transmitted at the end of all responses

Ex 1 : A (c r) = No data requested.123456 48 (cr) = Count data requested Ex 2 : APC

ERROR RESPONSE FORMAT

If the ID numbers match but the command is not valid or cannot be executed, the counter ignores the command and responds by sending an ASCII "N" (not acknowledged), followed by one character and carriage return.

XERROR CODES

N O 2 : CHECKSUM ERROR

Received checksum does not match the calculated check sum.

Incorrect number of digit or illegal characters received in data field.

N 1 1 : RESET EDIT IN PROGRESS ON KEY BOARD

Serial preset cannot be sent if the preset is being changed on the key board.

N 1 3 : KEY BOARD PROGRAM MODE IS ACTIVE

Cannot enter serial the PROGRAM MODE if in the key board PROGRAM MODE.

N F F : UNDER OVERFLOW or UNDERFLOW FOR COUNT VALUE

It is impossible to communicate under displaying for overflow error or underflow error. It is possible to communicate by reset command for error cancellation as the exception.

EX1: N05 (cr) = Invalid data

◆ RS-485 SERIAL INTERFACE

WAY OF COMMUNICATION Half duplex, Asynchronous

ASCII code FORMAT Start bit 1 bit Data bit 8 bit (including parity bit)
Stop bit 1 bit Parity bit 1 bit 300/600/1200/2400/4800/9600 bps (Selection)

BAUD RATE

PARITY NON/ODD/EVEN (Selection)

SERIAL COMMUNICATION (2)

◆ EXPLATION FOR COMMUNICATION COMMAND

1. RDD (XX) : Read Count value / Preset value

●This requires sub command with two(2)figures(XX). In accordance with required data, sub command is decided.

The response are shown as [sub command] [data] [check sum] [Cr] in order.

The decimal point positioning is also shown the same as the display of counter in this response.

The zero [0] in needless is read as a space.

Example for read : >01RDDPCCE(cr) = Read preset count value in unit No. 01.

Example for answer: APC -123.45 4D(cr) = preset count value -123.45.

Communication sub command. (XX) Contents of command Preset count value * Communication sub command is different ВС Batch count value ΤC Total count value according to each models Tachometer value TMP 1 1 level preset value 2 level preset value 3 level preset value 4 level preset value PWPrewarn value ВР Batch preset value Items selected for SEND DATA in the PROGRAM MODE SO

2. RDI (XX) Read Count value/Tachometer value(the value of integral)

3. RDU (XX) : Read Count value/Tachometer value(the value of under decimal point)

This command works the same as RDD command. Only 3 kind of sub command as shown below are available.

●RDI is the command to read the value of integral part in count value or tachometer value.

lacktriangle RDU is the command to read the value under the decimal point in count value or tachometer value.

Example for send: >10RDUPCDF(cr) = Read the preset count value in unit No. 10.

Example for response: APC. 12000000 64(cr) = Preset count value(under the decimal point): 12.

PC Preset count value
TC Total count value
TM Tachometer value

$4. \ \ \mathrm{WRD} \ \ (\mathrm{XX})$: Set the preset value.

- ●This requires sub command with 2(two)figures (XX). In accordance with the contents of command, sub command is decided as shown below.
- The response is [A] (cr) only.
- The decimal point position can not be set by WRD command. The decimal point is shown at the the position set in the program mode.

Example for send : >10WRDP1001234F9(cr) = set 1 level preset value in the unit No. (ID No.)10.

Communication sub command. (XX) Contents of command P 1 1 level preset value P 2 2 level preset value * Communication sub command is different Р3 3 level preset value according to each models. P 4 4 level preset value PWPrewarn value ВP Batch preset value

5. RES (XX) : Reset

- ●This requires sub command with two(2) figures (XX). In accordance with the contents of command the sub command is decided as shown below.
- ●The response is [A] (cr) only.
- ●This command works same as front reset key operation or reset input.

Example for send: >00RESPCDD(cr) = Reset preset count value in unit No. (ID No.)00.

Communication sub command. (XX)

Preset count value
BC

Preset count value
Batch preset value

Reset count value
Batch preset value

TC Total count value
ER Cancelling for error condition(over, under flow)

6. RDO : Read output condition (respective condition in out 1 - out 4)

Example for send: >00RD045(cr) = Read output condition in unit No. 00

lacktriangle The response is shown [A] [OUT 1 (HorL)] - [OUT 4 (HorL)] [Check sum)] (cr) in order.

Example for response: A1L2H3L4LF6(cr) = The output condition are as shown below in this example for response.

**OUT1 ~OUT 4 is different according to each models.

1 L	OUT1	\rightarrow	Low
2 H	OUT 2	\rightarrow	H i
3 L	OUT3	\rightarrow	Low
4 L	OUT4	\rightarrow	Low
1			

7. STP: Count prohibition

8. RSM: Cancellation for count prohibition

- ●When STP command is sent to the counter, counter does not enter any count input pulse until the counter received RSM command.
- ●Count prohibition will be cancelled when the power supply of counter is cut off. When the power supply of counter turns on, counter begins to accept the input pulse.
- The response is [A] (cr) only.

Example for send: >00STP57(cr) = Count prohibition in unit No. 00. >00RSM52(cr) = Cancellation for count prohibition in unit No. 00.

9. LTD (XX) : Store count value, tachometer value or preset value in the memory

●This requires sub command with two(2) figures. In accordance with the contents of command, sub command is decided as shown below.

●The data which can be memorized by this command is only one (1)item per once. In case this command is carried out newly, new data will be memorized instead of previous data.

The response is [A] (cr) only.

When the power supply of counter is cut off, the memorized data will be deleted.

Example for send: >00LTDPCD7(cr) = Store preset count value of unit No. 00. in its memory

ommunication sub command (XX)	Contents of command	
PC	Preset count value	
ВС	Batch count value	Communication command is different
TC	Total count value	according to each models.
TM	Tachometer value	
P 1	1 level preset value	
P 2	2 level preset value	
P 3	3 level preset value	
P 4	4 level preset value	
PW	Prewarn value	
BP	Batch preset value	
	-	

1 O. RLD : Read the data stored by LTD command

- The response is shown as [sub command][data][check sum][cr] in order.
- •In this response, the decimal point position showed on the display is also sent.
- The zero [0] in needless are sent as a space.
- •If the RLD command is carried out before the data is stored by LTD command, the response will be error code.

Example for send: >00RLD42(cr) = Read the stored data of unit No(ID No.) 00 in its memory.

Example for response: APC -123.45 4D(cr) = Preset count value -123.45.

◆EASY COMMUNICATION (COMMUNICATION REQUEST)

• Easy communication (Communication request)

For the way of easy communication, there is the function named communication request in this counter. By shorting the terminal of "communication request" and "GND", it reads the data set for SEND DATA in the program mode.

Example for set: When the data of the preset count value and 1 level preset value are set for SEND DATA in the PROGRAM MODE.

Example for response: APC 123.00 P1 200.00 58(cr)

The above example shows : Preset count value is 123.00 1 level preset value is 200.00

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